

**Mathematical physics-1**  
**(Solved Paper - 2015)**

Q. 1 (a). By calculating the Wronskian of the function  $-1, \sin^2 x, \cos^2 x$ , check whether the function are linearly dependent or independent. 4

Ans.

$$y_1 = -1, y_2 = \sin^2 x, y_3 = \cos^2 x$$

$$y_1' = 0,$$

$$y_2' = 2 \sin x \cos x, \\ = \sin 2x$$

$$y_3' = 2 \cos x (-\sin x) \\ = -2 \sin x \cos x \\ = -\sin 2x$$

$$y_1'' = 0; y_2'' = 2 \cos 2x; y_3'' = -2 \cos 2x$$

$$W = \begin{vmatrix} y_1 & y_2 & y_3 \\ y_1' & y_2' & y_3' \\ y_1'' & y_2'' & y_3'' \end{vmatrix}$$

$$= \begin{vmatrix} -1 & \sin^2 x & \cos^2 x \\ 0 & \sin 2x & -\sin 2x \\ 0 & 2 \cos 2x & -2 \cos 2x \end{vmatrix}$$

$$= (-1)[-2 \sin 2x \cos 2x + 2 \cos 2x \sin 2x] \\ = 0$$

The system is linearly dependent.

**Q1(b): Solve**

$$y(xy + 2x^2y^2) dx + x(xy - x^2y^2) dy = 0 \quad \dots\dots\dots (1)$$

**Sol: Dividing (1) by  $xy$ , we get**

$$y(1+2xy) dx + x(1-xy) dy = 0 \quad \dots (2)$$

$$M = y f_1(xy), \quad N = x f_2(xy)$$

$$\text{I.F.} = \frac{1}{Mx - Ny} = \frac{1}{xy(1+2xy) - xy(1-xy)} = \frac{1}{3x^2y^2}$$

On multiplying (2) by  $\frac{1}{3x^2y^2}$ , we have an exact differential equation

$$\left(\frac{1}{3x^2y} + \frac{2}{3x}\right) dx + \left(\frac{1}{3xy^2} - \frac{1}{3y}\right) dy = 0 \Rightarrow \int \left(\frac{1}{3x^2y} + \frac{2}{3x}\right) dx + \int -\frac{1}{3y} dy = c$$

$$\Rightarrow -\frac{1}{3xy} + \frac{2}{3} \log x - \frac{1}{3} \log y = c \Rightarrow -\frac{1}{xy} + 2 \log x - \log y = b$$

Q1(c)

(c). Solve the differential equation

$$\frac{d^2y}{dx^2} - 2\frac{dy}{dx} + y = e^x + x$$

Sol

Given equation is

$$\frac{\partial^2 y}{\partial x^2} - 2\frac{\partial y}{\partial x} + y = e^x + x$$

Auxiliary equation is

$$m^2 - 2m + 1 = 0$$

$$m = \frac{2 \pm \sqrt{4-4}}{2} = 1, 1$$

$$\text{Cf.} = (c_1 + c_2 x) e^x$$

particular solution, P.I =  $\frac{e^x}{D^2 - 2D + 1}$

$$= \frac{e^x}{1 - 2 + 1} \quad \because \text{Here denominator} = 0$$

Again, P.I =  $\frac{x e^x}{2D - 2}$  again denominator = 0

Again P.I =  $\frac{x^2 e^x}{2}$

$$\frac{x}{D^2 - 2D + 1} = \frac{x}{(1 + D^2 - 2D)^{-1}} = x(1 + D^2 - 2D)^{-1}$$

$$\Rightarrow x(1 - D^2 + 2D) = x - D^2 x + 2Dx$$

$$\Rightarrow \frac{x}{D^2 - 2D + 1} = x - 0 + 2x = x + 2$$

$\therefore$  Complete solution is

$$y = (C_1 + C_2 x)e^x + \frac{x^2 e^x}{2} + x + 2$$



Q.2 (a). Solve the differential equation:

$$\frac{d^2 y}{dx^2} - 4y = x \sin x$$

Ans.  $\frac{d^2 y}{dx^2} - 4y = x \sin x$

The auxiliary equation is  $m^2 - 4 = 0$

$$\Rightarrow m^2 = 4 \Rightarrow m = \pm 2$$

$$\therefore \text{C.F.} = C_1 e^{2x} + C_2 e^{-2x}$$

$$\text{P.I.} = I \frac{1}{(D^2 - 4)} x \sin x$$

$$= I \frac{1}{(D^2 - 4)} x e^{ix}$$

$$= I e^{ix} \frac{1}{[(D+i)^2 - 4]} \cdot x$$

$$= I e^{ix} \frac{1}{[D^2 + 2Di + i^2 - 4]} \cdot x$$

$$= I e^{ix} \frac{1}{[D^2 + 2Di - 5]} \cdot x$$

$$= \frac{1}{5} I e^{ix} \frac{1}{\left[ \frac{D^2 + 2Di - 1}{5} \right]} \cdot x$$

$$\begin{aligned}
 &= -\frac{1}{5} I e^{ix} \left[ \frac{1}{1 - \frac{D^2 + 2Di}{5}} \right] \cdot x \\
 &= -\frac{I}{5} e^{ix} \left[ 1 - \frac{D^2 + 2Di}{5} \right]^{-1} \cdot x \\
 &= -\frac{I}{5} e^{ix} \left[ 1 + \frac{D^2 + 2Di}{5} \right] \cdot x
 \end{aligned}$$

Using Binomial Theorem upto 2<sup>nd</sup> term

$$\begin{aligned}
 P.I. &= -\frac{I}{5} e^{ix} \left[ x + \frac{1}{5} \frac{\partial^2}{\partial x^2} (x) + \frac{2}{5} \frac{\partial}{\partial x} (x) i \right] \\
 &= -\frac{I}{5} e^{ix} \left[ x + \frac{2}{5} i \right]
 \end{aligned}$$

$$= -\frac{I}{5} (\cos x + i \sin x) \left( x + \frac{2}{5} i \right)$$

$$= -\frac{I}{5} \left[ x \cos x + \frac{2}{5} i \cos x + \frac{2}{5} i^2 \sin x + ix \sin x \right]$$

$$= -\frac{I}{5} \left[ \left( x \cos x - \frac{2}{5} \sin x \right) + i \left( \frac{2}{5} \cos x + x \sin x \right) \right]$$

∴ P.I. = Imaginary part

$$= -\frac{1}{5} \left( \frac{2}{5} \cos x + x \sin x \right)$$

Solution = C.F. + P.I.

(b). Solve the differential equation using method of undetermined coefficients :

$$\frac{d^2 y}{dx^2} - 4 \frac{dy}{dx} + 4y = x^2 + \cos 2x \quad 8$$

$$\text{Ans. } \frac{d^2 y}{dx^2} - 4 \frac{dy}{dx} + 4y = x^2 + \cos 2x$$

The auxiliary equation is  $m^2 - 4m + 4 = 0$

$$\text{or } (m - 2)^2 = 0 \Rightarrow m = 2, 2$$



$$\text{C.F.} = (C_1 + C_2 x)e^{2x}$$

$$\text{P.I.} = \frac{x^2}{D^2 - 4D + 4} + \frac{\cos 2x}{D^2 - 4D + 4}$$

$$\frac{x^2}{D^2 - 4D + 4} = \frac{x^2}{4 \left( \frac{1 + D^2 - 4D}{4} \right)}$$

$$= \frac{1}{4} \left( 1 + \frac{D^2 - 4D}{4} \right)^{-1} \cdot x^2$$

$$= \frac{1}{4} \left[ 1 - \left( \frac{D^2 - 4D}{4} \right) + \left( \frac{D^2 - 4D}{4} \right)^2 \right] x^2$$

$$= \frac{1}{4} \left[ 1 - \frac{D^2}{4} + D + \frac{D^4}{16} - \frac{16D^2}{16} + \frac{8D^3}{16} \right] x^2$$

$$= \frac{1}{4} \left[ x^2 - \frac{1}{4} D^2 x^2 + D x^2 + \frac{1}{16} D^4 x^2 + D^2 x^2 \right.$$

$$\left. - \frac{1}{2} D^3 x^2 \right]$$

$$= \frac{1}{4} \left[ x^2 - \frac{1}{4} \cdot 2 + 2x + 0 + 2x - 0 \right]$$

$$= \frac{1}{4} \left[ x^2 + 4x - \frac{1}{2} \right]$$

$$= \frac{1}{4} x^2 + x - \frac{1}{8}$$

$$\frac{\cos 2x}{D^2 - 4D + 4} = \frac{\cos 2x}{-4 - 4D + 4} = \frac{\cos 2x}{4D}$$

$$= \frac{1}{4} \cdot \frac{D \cos 2x}{D \cdot D} = \frac{1}{4} \cdot \frac{D \cos 2x}{(-4)} = \frac{1}{16} D \cos 2x$$

$$= \frac{1}{16} (-2 \sin 2x) = -\frac{1}{8} \sin 2x$$

$$\therefore \text{P.I. is } \frac{1}{4}x^2 + x - \frac{1}{8} - \frac{1}{8}\sin 2x$$

The soln is C.F. + P.I.

Q. 3(a). Solve the differential equation

$$\frac{d^2y}{dx^2} - \frac{dy}{dx} - 2y = 10 \cos x$$

given  $y(0) = 1$   $y'(0) = -1$ .

Solution

Given equation is

$$\frac{d^2y}{dx^2} - \frac{dy}{dx} - 2y = 10 \cos x$$

Auxiliary equation is

$$(m^2 - m - 2) = 0$$

$$m = \frac{1 + \sqrt{1+8}}{2} = \frac{1+3}{2}$$

$$= 2, -1$$

$$\therefore y = C_1 e^{2x} + C_2 e^{-x}$$

particular Integral,  $P.I = \frac{10 \cos x}{[D^2 - D - 2]}$



$$\Rightarrow P I = \frac{10 \cos x}{-1 - D - 2} = \frac{10 \cos x}{-3 - D}$$

$$\Rightarrow P I = \frac{-10 \cos x}{D + 3}$$

Multiplying num. & denominator by  $D-3$

$$P I = \frac{-10 \cos x (D-3)}{D+3 (D-3)} = \frac{-10 \cos x (D-3)}{D^2 - 9}$$

$$= \frac{+10 \sin x + 30 \cos x}{-1 - 9}$$

$$= -\sin x - 3 \cos x$$

$\therefore$  complete solution is

$$y = C_1 e^{2x} + C_2 e^{-x} - \sin x - 3 \cos x \quad \text{--- (1)}$$

Given  $y = 1$  at  $x = 0$

Putting this in equation 1,

$$1 = C_1 + C_2 - 3 \Rightarrow \boxed{C_1 + C_2 = 4} \quad \text{--- (2)}$$

Also,  $y' = -1$  at  $x = 0$

$$\frac{dy}{dx} = 2C_1 e^{2x} + C_2 e^{-x} (-1) - \cos x + 3 \sin x$$

Putting  $x = 0$  &  $y' = -1$

$$-1 = 2C_1 - C_2 - 1$$

$$\Rightarrow \boxed{2C_1 - C_2 = 0} \quad \text{--- (3)}$$



on solving (2) and (3) we get

$$C_1 = \frac{4}{3} \quad \text{and} \quad C_2 = \frac{8}{3}$$

∴ complete solution is given by

$$y = \frac{4}{3} e^{2x} + \frac{8}{3} e^{-x} - \sin x - 3 \cos x.$$

3(b)

(b). Solve the differential equation using method of variation of parameters

$$\frac{d^2 y}{dx^2} + a^2 y = \sec ax$$

Sol

Sol: Given equation is

$$\frac{d^2 y}{dx^2} + a^2 y = \sec ax.$$

Auxillary eq<sup>n</sup> is  $m^2 + a^2 = 0 \Rightarrow m^2 = -a^2$

$$m = \pm ia.$$

complementary function is

$$Cf = A \cos ax + B \sin ax.$$

Here,  $y_1 = \cos ax$        $y_2 = \sin ax$

$$W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = \begin{vmatrix} \cos ax & \sin ax \\ -\sin ax(a) & \cos ax(a) \end{vmatrix}$$

$$W = a \cos^2 ax + a \sin^2 ax = a$$

Now, P.I. =  $u y_1 + v y_2$ .

$$\begin{aligned} u &= -\int \frac{y_2 \sec ax \, dx}{W} = -\int \frac{\sin ax \sec ax \, dx}{a} \\ &= -\frac{1}{a} \int \tan ax \, dx = -\frac{1}{a^2} \log(\sec ax) \\ &= \frac{\log(\cos ax)}{a^2} \end{aligned}$$

$$\begin{aligned} \text{Now, } v &= \int \frac{y_1 \sec ax \, dx}{W} = \int \frac{\cos ax \sec ax \, dx}{a} \\ &= \frac{x}{a} \end{aligned}$$

$$\therefore \text{P.I.} = \frac{\cos ax \log \cos ax}{a^2} + \frac{x}{a} \sin ax$$

$$\text{Reqd. sol, } y = A \cos ax + B \sin ax + \frac{\cos ax \log \cos ax}{a^2} + \frac{x}{a} \sin ax.$$



Q. 4(a). Find the volume of a parallelepiped whose sides are given by  $\vec{A} = 2\hat{i} + 3\hat{j} - \hat{k}$ ,  $\vec{B} = \hat{i} - \hat{j} - 2\hat{k}$  and  $\vec{C} = -\hat{i} + 2\hat{j} + 2\hat{k}$ . 3

Ans. 
$$\begin{aligned}\vec{A} &= 2\hat{i} + 3\hat{j} - \hat{k} &= A_1\hat{i} + A_2\hat{j} + A_3\hat{k} \\ \vec{B} &= \hat{i} - \hat{j} - 2\hat{k} &= B_1\hat{i} + B_2\hat{j} + B_3\hat{k} \\ \vec{C} &= -\hat{i} + 2\hat{j} + 2\hat{k} &= C_1\hat{i} + C_2\hat{j} + C_3\hat{k}\end{aligned}$$

Volume of a parallelepiped =  $\vec{A} \cdot (\vec{B} \times \vec{C})$

$$= \vec{B} \cdot (\vec{C} \times \vec{A})$$

$$= \vec{C} \cdot (\vec{A} \times \vec{B})$$

Also,

$$V = \begin{vmatrix} A_1 & A_2 & A_3 \\ B_1 & B_2 & B_3 \\ C_1 & C_2 & C_3 \end{vmatrix}$$

$$= \begin{vmatrix} 2 & 3 & -1 \\ 1 & -1 & -2 \\ -1 & 2 & 2 \end{vmatrix}$$

$$= 2 \begin{vmatrix} -1 & -2 \\ 2 & 2 \end{vmatrix} - 1 \begin{vmatrix} 3 & -1 \\ 2 & 2 \end{vmatrix} - 1 \begin{vmatrix} 3 & -1 \\ -1 & -2 \end{vmatrix}$$

$$= 2(-2 + 4) - 1(6 + 2) - 1(-6 - 1)$$

$$= 4 - 8 + 7$$

$$= 3 \text{ Cubic units.}$$

(b). Calculate the Jacobian  $J\left(\frac{x, y, z}{u, v, w}\right)$  of the transformation  $x = u^2$

+  $w$ ,  $y = u + v$  and  $z = w^2 - u$ . 3

$$J \left( \frac{x, y, z}{u, v, w} \right) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}$$

$$x = u^2 + w$$

$$y = v + v$$

$$z = w^2 - u$$

$$J \left( \frac{x, y, z}{u, v, w} \right) = \begin{vmatrix} 2u & 0 & 1 \\ 1 & 1 & 0 \\ -1 & 0 & 2w \end{vmatrix}$$

$$= 2u(2w) + 1(1)$$

$$= 4uw + 1 \quad \text{Ans.}$$



(c). If  $\vec{v} = \vec{w} \times \vec{r}$ , find whether  $\vec{v}$  is solenoidal or not, where,  $\vec{w}$  is a constant vector and  $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$ . 3

Ans. Let  $\vec{w} = A_1\hat{i} + A_2\hat{j} + A_3\hat{k}$

And  $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$

$$\vec{w} \times \vec{r} = (A_1\hat{i} + A_2\hat{j} + A_3\hat{k}) \times (x\hat{i} + y\hat{j} + z\hat{k})$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_1 & A_2 & A_3 \\ x & y & z \end{vmatrix}$$

$$= (A_2z - A_3y)\hat{i} - (A_1z - A_3x)\hat{j} + (A_1y - A_2x)\hat{k}$$

$$\text{Div. } \vec{V} = \left( \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot [(A_2z - A_3y)\hat{i} - (A_1z - A_3x)\hat{j} + (A_1y - A_2x)\hat{k}]$$

$$= \frac{\partial}{\partial x}(A_2z - A_3y)x^2 - \frac{\partial}{\partial y}(A_1z - A_3x)y^2$$

$$+ \frac{\partial}{\partial z}(A_1y - A_2x)z^2$$

$$= 0 - 0 + 0$$

$$= 0$$

Hence  $\vec{V}$  is solenoidal.

(d). Find,  $\vec{\nabla} \cdot (f(r)\vec{r})$  where  $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$ . 3

Ans. Pl. ref. your text.

(e). Find the directional derivative of a scalar function  $\phi = (x^2 + y^2 + z^2)^{1/2}$  at the point  $P(3, 1, 2)$  in the direction of the vector  $yzi\hat{i} + xz\hat{j} + xy\hat{k}$ . 3

Ans.  $\phi = (x^2 + y^2 + z^2)^{1/2}$

$$\vec{a} = yzi\hat{i} + xz\hat{j} + xy\hat{k}$$

Unit vector in the direction of given vector

$$\hat{a} = \frac{yzi + zxj + xyk}{\sqrt{y^2z^2 + z^2x^2 + x^2y^2}}$$

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= -\frac{1}{2}(x^2 + y^2 + z^2)^{-3/2}(2x) \\ &= -x(x^2 + y^2 + z^2)^{-3/2}\end{aligned}$$

Similarly,

$$\frac{\partial\phi}{\partial y} = -y(x^2 + y^2 + z^2)^{-3/2}$$

And

$$\frac{\partial\phi}{\partial z} = -z(x^2 + y^2 + z^2)^{-3/2}$$

$$\begin{aligned}\text{grade } \phi &= i\frac{\partial\phi}{\partial x} + j\frac{\partial\phi}{\partial y} + k\frac{\partial\phi}{\partial z} \\ &= -x(x^2 + y^2 + z^2)^{-3/2}(xi + yj + zk)\end{aligned}$$

$$\begin{aligned}\therefore \frac{\partial\phi}{\partial S} &= \hat{a} \cdot \text{grade } \phi \\ &= \frac{yzi + zxj + xyk}{\sqrt{y^2z^2 + z^2x^2 + x^2y^2}} \cdot \left[ -(x^2 + y^2 + z^2)^{-3/2} \right. \\ &\quad \left. (xi + yj + zk) \right]\end{aligned}$$

$$= \frac{-3xy(x^2 + y^2 + z^2)^{-3/2}}{\sqrt{y^2z^2 + z^2x^2 + x^2y^2}}$$

$\frac{\partial\phi}{\partial S}$  at P(3, 1, 2) is

$$= \frac{-3(6)(9+1+4)^{-3/2}}{\sqrt{4+36+9}}$$

$$= \frac{-18(14)^{-3/2}}{7}$$

$$= \frac{-18}{7 \times 14\sqrt{14}}$$



$$= \frac{-9}{49\sqrt{14}}$$

$$\left| \frac{\partial \phi}{\partial S} \right| = \frac{9}{49\sqrt{14}}$$

Q. 5(a). Prove that,

$$(\vec{A} \times \vec{B}) \cdot (\vec{C} \times \vec{D}) = (\vec{A} \cdot \vec{C})(\vec{B} \cdot \vec{D}) - (\vec{A} \cdot \vec{D})(\vec{B} \cdot \vec{C}) \quad 3$$

Ans.  $(\vec{A} \times \vec{B}) \cdot (\vec{C} \times \vec{D}) = (\vec{A} \cdot \vec{C})(\vec{B} \cdot \vec{D}) - (\vec{A} \cdot \vec{D})(\vec{B} \cdot \vec{C})$

Put  $\vec{C} \times \vec{D} = \vec{r}$

L.H.S.  $= (\vec{A} \times \vec{B}) \cdot \vec{r}$

$$= \vec{A} \cdot (\vec{B} \times \vec{r}) \quad \dots \text{Dot and cross can be exchanged.}$$

$$= \vec{A} \cdot [\vec{B} \times (\vec{C} \times \vec{D})]$$

$$= \vec{A} \cdot [(\vec{B} \cdot \vec{D})\vec{C} - (\vec{B} \cdot \vec{C})\vec{D}]$$

$$= (\vec{A} \cdot \vec{C})(\vec{B} \cdot \vec{D}) - (\vec{A} \cdot \vec{D})(\vec{B} \cdot \vec{C})$$

$$= \text{R.H.S.}$$

Hence proved.

(b). Evaluate

$$\vec{\nabla} \left[ \vec{\nabla} \cdot \left( \frac{\vec{r}}{r^2} \right) \right]$$

where  $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$

Sol:

$$\vec{\nabla} \left[ \vec{\nabla} \cdot \left( \frac{\vec{r}}{r^2} \right) \right]$$

$$\vec{r} = x \hat{i} + y \hat{j} + z \hat{k}$$

$$r^2 = x^2 + y^2 + z^2$$

$$\frac{\vec{r}}{r^2} = \frac{x}{x^2+y^2+z^2} \hat{i} + \frac{y}{x^2+y^2+z^2} \hat{j} + \frac{z}{x^2+y^2+z^2} \hat{k}$$

$$= A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$$\vec{\nabla} \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

$$= \frac{y^2+z^2-x^2}{(x^2+y^2+z^2)^2} + \frac{x^2-y^2+z^2}{(x^2+y^2+z^2)^2} + \frac{x^2+y^2-z^2}{(x^2+y^2+z^2)^2}$$

$$= \frac{x^2+y^2+z^2}{(x^2+y^2+z^2)^2} = \frac{1}{x^2+y^2+z^2}$$

$$\vec{\nabla} (\vec{\nabla} \cdot \vec{A}) = \frac{\partial (\vec{\nabla} \cdot \vec{A})}{\partial x} \hat{i} + \frac{\partial (\vec{\nabla} \cdot \vec{A})}{\partial y} \hat{j} + \frac{\partial (\vec{\nabla} \cdot \vec{A})}{\partial z} \hat{k}$$



$$= \frac{-2x}{x^2+y^2+z^2} \hat{i} - \frac{2y}{x^2+y^2+z^2} \hat{j} - \frac{2z}{x^2+y^2+z^2} \hat{k}$$

$$= \frac{-2(x \hat{i} + y \hat{j} + z \hat{k})}{x^2+y^2+z^2} = \underline{\underline{\frac{-2\vec{r}}{r^2}}}$$

(c). Evaluate

$$I = \int_C (3x^2 - 8y^2) dx + (4y - 6xy) dy$$

where C is the boundary of the region defined by  $y^2 = x$  and  $y = x^2$ .

Ans. See Book portion for solution

Q. 6(a). Verify Stoke's theorem for

$$\vec{A} = (2x - y)\hat{i} - yz^2\hat{j} - y^2z\hat{k}$$

where S is the upper half surface of the sphere  $x^2 + y^2 + z^2 = 1$  and C is its boundary. 10

Ans.  $\vec{A} = (2x - y)\hat{i} - yz^2\hat{j} - y^2z\hat{k}$

$$\int_C \vec{A} \cdot d\vec{r} = \oint_C (A_x dx + A_y dy + A_z dz)$$

$$= \int_C \{(2x - y)dx - yz^2 dy - y^2 z dz\}$$

But the boundary C of S is a circle in the  $xy$ -plane of radius unity and centre at (0, 0, 0), Hence the parametric equations of C are :

$$x = \cos \theta$$

$$y = \sin \theta$$

$$z = 0, \text{ where } \theta \text{ varies}$$

From 0 to  $2\pi$ , Thus

$$\int_C \vec{A} \cdot d\vec{r} = \int_{\theta=0}^{2\pi} \{(2 \cos \theta - \sin \theta)(-\sin \theta d\theta) - 0 - 0\}$$

$$= - \int_0^{2\pi} (2 \cos \theta - \sin \theta) \sin \theta d\theta$$

$$= - \int_0^{2\pi} (\sin 2\theta - \sin^2 \theta) d\theta$$

$$= - \int_0^{2\pi} \left( \sin 2\theta - \frac{1 - \cos 2\theta}{2} \right) d\theta$$

$$= - \left[ \frac{\cos 2\theta}{2} - \frac{\theta}{2} + \frac{\sin 2\theta}{2} \right]_0^{2\pi}$$

$$= \pi$$

Now,

$$\nabla \times \vec{A} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ (2x - y) & -yz^2 & -y^2z \end{vmatrix}$$

$$= k$$



$$\begin{aligned} \text{Hence, } \iint_S (\nabla \times \vec{A}) \cdot d\vec{s} &= \iint_S k \cdot d\vec{s} \\ &= \iint_R dx dy, \end{aligned}$$

where R is the projection of S on xy-plane and  $k \cdot d\vec{s} = dx dy =$  projection of  $d\vec{s}$  on xy-plane.

$$\text{Thus, } R \text{ is } x^2 + y^2 = 1$$

$$\therefore \iint_R dx dy = 4 \int_0^1 \int_0^1 \sqrt{1-x^2} dx dy$$

$$= 4 \int_0^1 \sqrt{1-x^2} dx$$

$$= 4 \left[ \frac{x}{2} \sqrt{1-x^2} + \frac{1}{2} \sin^{-1} x \right]_0^1$$

$$= 4 \cdot \frac{\pi}{4}$$

$$= \pi$$

$$\text{Hence, } \int_C \vec{A} \cdot d\vec{r} = \iint_S (\nabla \times \vec{A}) \cdot d\vec{s}$$

This verifies stoke's theorem.

(b) Using Gauss Divergence theorem, prove that

$$\iiint_V \nabla \phi dV = \iint_S \phi d\vec{S}$$

where V is the volume enclosed by the surface S.

In the divergence theorem, let  $\mathbf{A} = \phi \mathbf{C}$  where  $\mathbf{C}$  is a constant vector. Then

$$\iiint_V \nabla \cdot (\phi \mathbf{C}) dV = \iint_S \phi \mathbf{C} \cdot \mathbf{n} dS$$

Since  $\nabla \cdot (\phi \mathbf{C}) = (\nabla \phi) \cdot \mathbf{C} = \mathbf{C} \cdot \nabla \phi$  and  $\phi \mathbf{C} \cdot \mathbf{n} = \mathbf{C} \cdot (\phi \mathbf{n})$ ,

$$\iiint_V \mathbf{C} \cdot \nabla \phi dV = \iint_S \mathbf{C} \cdot (\phi \mathbf{n}) dS$$

Taking  $\mathbf{C}$  outside the integrals,

$$\mathbf{C} \cdot \iiint_V \nabla \phi dV = \mathbf{C} \cdot \iint_S \phi \mathbf{n} dS$$

and since  $\mathbf{C}$  is an arbitrary constant vector,

$$\iiint_V \nabla \phi dV = \iint_S \phi \mathbf{n} dS$$



Q. 7(a) Derive an expression of divergence of a vector field in orthogonal curvilinear coordinates. Express it in cylindrical coordinates.

Ans. Let  $f(u, v, w)$  be a vector point function of orthogonal curvilinear coordinates  $u, v, w$ .

$$\begin{aligned} \text{Divergence } \bar{f} &= \nabla \cdot \bar{f} \\ &= \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial}{\partial u} (h_2 h_3 f_1) + \frac{\partial}{\partial v} (h_3 h_1 f_2) + \frac{\partial}{\partial w} (h_1 h_2 f_3) \right] \end{aligned}$$

$$\begin{aligned} \text{Proof. Let } \bar{f} &= f_1 \bar{T}_u + f_2 \bar{T}_v + f_3 \bar{T}_w \\ &= f_1 \bar{T}_v \times \bar{T}_w + f_2 \bar{T}_w \times \bar{T}_u + f_3 \bar{T}_u \times \bar{T}_v \\ &= f_1 h_2 h_3 \nabla v \times \nabla w + f_2 h_3 h_1 \nabla w \times \nabla u + f_3 h_1 h_2 \nabla u \times \nabla v \end{aligned}$$

$$\begin{aligned} \text{Divergence } \bar{f} &= \nabla \cdot \bar{f} \\ &= \nabla \cdot [f_1 h_2 h_3 \nabla v \times \nabla w + f_2 h_3 h_1 \nabla w \times \nabla u + f_3 h_1 h_2 \nabla u \times \nabla v] \\ &= \nabla \cdot (f_1 h_2 h_3 \nabla v \times \nabla w) + \nabla \cdot (f_2 h_3 h_1 \nabla w \times \nabla u) \\ &\quad + \nabla \cdot (f_3 h_1 h_2 \nabla u \times \nabla v) \\ \nabla \cdot (f_1 h_2 h_3 \nabla v \times \nabla w) &= f_1 h_2 h_3 \nabla \cdot (\nabla v \times \nabla w) + (\nabla v \times \nabla w) \cdot \nabla (f_1 h_2 h_3) \end{aligned}$$

$$\begin{aligned} &= f_1 h_2 h_3 [\text{curl } \nabla v \cdot \nabla w - \text{curl } \nabla w \cdot \nabla v] \\ &\quad + [\nabla v \times \nabla w] \cdot \nabla (f_1 h_2 h_3) \\ &= f_1 h_2 h_3 [\text{curl grade } v \cdot \nabla w - \text{curl grade } w \cdot \nabla v] \\ &\quad + [\nabla v \times \nabla w] \cdot \nabla (f_1 h_2 h_3) \\ &= (\nabla v \times \nabla w) \cdot \nabla (f_1 h_2 h_3) \end{aligned}$$

$$\begin{aligned}
&= (\nabla v \times \nabla w) \cdot \left[ \frac{\partial}{\partial u} (f_1 h_2 h_3) \nabla u + \frac{\partial}{\partial v} (f_1 h_2 h_3) \nabla v + \frac{\partial}{\partial w} (f_1 h_2 h_3) \nabla w \right] \\
&= (\nabla v \times \nabla w) \cdot \nabla u \frac{\partial}{\partial u} (f_1 h_2 h_3) \quad \left[ \begin{array}{l} \nabla v \times \nabla w \cdot \nabla v = 0 \\ \nabla v \times \nabla w \cdot \nabla w = 0 \end{array} \right] \\
&= \frac{1}{h_1 h_2 h_3} (T_v \times T_w) \cdot T_u \frac{\partial}{\partial u} (f_1 h_2 h_3) \\
&= \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial u} (f_1 h_2 h_3) [(T_v \times T_w) \cdot T_u = T_u \cdot T_u = 1]
\end{aligned}$$

By symmetry

$$\nabla \cdot (f_2 h_3 h_1 \nabla w \times \nabla u) = \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial v} (f_2 h_3 h_1)$$

$$\text{and } \nabla \cdot (f_3 h_1 h_2 \nabla u \times \nabla v) = \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial w} (f_3 h_1 h_2)$$

On substituting the values

$$\begin{aligned}
\text{Div. } \vec{f} &= \nabla \cdot \vec{f} \\
&= \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial}{\partial u} (f_1 h_2 h_3) + \frac{\partial}{\partial v} (f_2 h_3 h_1) + \frac{\partial}{\partial w} (f_3 h_1 h_2) \right]
\end{aligned}$$

In cylindrical co-ordinates.

$$\begin{aligned}
\text{div. } \vec{F} &= \nabla \cdot \vec{F} \\
&= \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho F_\rho) + \frac{1}{\rho} \frac{\partial}{\partial \phi} F_\phi + \frac{\partial F_z}{\partial z}
\end{aligned}$$

(b) Evaluate

$$\iiint_V (x^2 + y^2 + z^2) dV$$

where V is the volume of the sphere  $x^2 + y^2 + z^2 = a^2$ .

6

$$\text{Ans. } \iiint_V (x^2 + y^2 + z^2) dV$$

... (i)

$$x^2 + y^2 + z^2 = a^2$$



$$\iiint_V (x^2 + y^2 + z^2) dv = \iiint_V (x^2 + y^2 + z^2) dx dy dz$$

Converting the given intergral into spherical polar co-ordinates.

Put,

$$\begin{aligned} x &= r \sin \theta \cos \phi \\ y &= r \sin \theta \sin \phi \\ z &= r \cos \theta \end{aligned}$$

$$\iiint_V (x^2 + y^2 + z^2) dx dy dz = \int_0^{2\pi} \int_0^{\pi} \int_0^a r^2 (r^2 \sin \theta d\theta d\phi dr)$$

$$= \int_0^{2\pi} d\phi \int_0^{\pi} \sin \theta d\theta \int_0^a r^4 dr$$

$$= \int_0^{2\pi} d\phi \int_0^{\pi} \sin \theta d\theta \left| \frac{r^5}{5} \right|_0^a$$

$$= \frac{a^5}{5} \int_0^{2\pi} d\phi \int_0^{\pi} \sin \theta d\theta$$

$$= \frac{a^5}{5} \int_0^{2\pi} d\phi (-\cos \theta)_0^{\pi}$$

$$= \frac{2a^5}{5} \int_0^{2\pi} d\phi$$

$$= \frac{2}{5} a^5 \cdot (2\pi)$$

$$= \frac{4\pi}{5} a^5$$

(c) Define the Dirac Delta function and establish

$$\int_{-\infty}^{\infty} f(x)\delta(x-a)dx = -f'(a)$$

Ans. 
$$\int_{-\infty}^{\infty} f(x)\delta(x-a)dx = -f'(a)$$

$$\begin{aligned}\int_{-\infty}^{\infty} f(x)\delta(x-a)dx &= [f(x)\delta(x-a)]_{-\infty}^{\infty} - \int_{-\infty}^{\infty} f'(x)\delta(x-a)dx \\ &= 0 - 0 - f'(a) \\ &= -f'(a)\end{aligned}$$

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